

Energy Reduction and Fundamental Energy Limits in Digital VLSI Circuits

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I. INTRODUCTION

Many, widely used building units in digital VLSI circuits take an input vector $x(k) \in \{0,1\}^n$ and produce an output vector $y(k) = F(x(k)) \in \{0,1\}^m$ at every clock cycle $k = 0, 1, \dots$. Examples of such units are, adders, multipliers etc. Associated to the operation F , there is a nonnegative cost $\mathcal{E}(x(k-1), x(k))$, that depends only on $x(k-1)$ and $x(k)$. There is also a communication unit, called bus, that simply reproduces the input vector at its output, i.e. $y = x$. We will use the bus as an example since its cost function is known [1]. We address the problem of deriving the minimum cost (energy), necessary for a unit to process a bit of information. We also address the use of coding in order to achieve this limit. Let $X : x(k), k = 0, 1, \dots$ be, a stationary random process in $\{0,1\}^n$, and input of a given unit with cost function \mathcal{E} .

Definition I.1 The utilization, $a(X) \in [0, 1]$, of the unit, by the process X is: $a(X) = \mathcal{H}(X)/n$.

Definition I.2 The energy cost per information bit corresponding to X is: $\mathcal{E}_b(X) = \mathcal{E}(x(k-1), x(k))/\mathcal{H}(X)$ where the over-line stands for expectation over $(x(k-1), x(k))$.

The function $\mathcal{E}_b(X)$ is, an induced by the unit, measure, of how efficiently the information is carried by the process X . It is important to relate $\mathcal{E}_b(X)$ to the corresponding utilization $a(X)$ of the unit by the process X . As shown in Figure 1 there are cases that the energy per bit can become arbitrary low for processes with arbitrary low entropy rate.

Definition I.3 The minimum energy required, per information bit processed by the unit, at utilization a' of the unit, is:

$$\mathcal{E}_b^*(a') = \inf_{a(X)=a'} \mathcal{E}_b(X)$$

where the infimum is taken over stationary processes.

II. RESULTS

Theorem II.1 [2] With the above setup and certain assumptions on the function \mathcal{E} ², for every $a \in [0, 1]$ there exists a unique nonnegative number γ such that:

$$\mathcal{E}_b^*(a) = \frac{\ln(2)}{\gamma - \frac{1}{\frac{\partial}{\partial \gamma} \ln(\ln(\mu(\gamma)))}} \quad (1)$$

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² Like for example $\mathcal{E}(x, y) = 0 \Leftrightarrow x = y$

$$a = -\frac{1}{n \ln(2)} \gamma^2 \frac{\partial}{\partial \gamma} \left(\frac{\ln(\mu(\gamma))}{\gamma} \right) \quad (2)$$

where $\mu(\gamma)$ is the maximal eigenvalue of the cost matrix

$$W(\gamma) = [e^{-\gamma \mathcal{E}(x,y)}]_{x,y \in \{0,1\}^n}$$

Furthermore, the minimum is attained by the stationary ergodic Markov process with transition probabilities:

$$\Pr(y|x) = \frac{1}{\mu(\gamma)} \frac{g_y}{g_x} e^{-\gamma \mathcal{E}(x,y)}$$

where $g = (g_x)_x$ is the right eigenvector of matrix $W(\gamma)$ corresponding to $\mu(\gamma)$.

Introducing and using the notion of energy typical sequences we can prove the following theorem.

Theorem II.2 [2] The minimum energy per information bit, given by (1), is asymptotically achievable using coding.

Example: For buses the energy cost is given by $\mathcal{E}(x, y) = E_0(y-x)^T C(y-x)$ where C is the symmetric tri-diagonal Toeplitz $(-\lambda, 1+2\lambda, -\lambda)$ matrix [1]. Figure 1 presents the ratio $\mathcal{E}_b^*(a)/\mathcal{E}_u$ as a function of the utilization a for $n = 8$ and $\lambda = 5$. \mathcal{E}_u is the expected energy per bit when $x(k), k = 0, 1, \dots$ are i.i.d. and uniformly distributed random vectors.

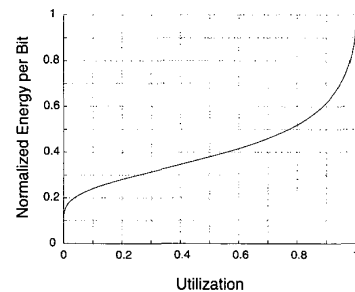


Figure 1: The function $\mathcal{E}_b^*(a)/\mathcal{E}_u$ for $n = 8$ and $\lambda = 5$.

Our results can be extended to units modelled as *Finite State Machines*. Other than energy costs objectives, like time for example, can be considered as well. There are some interesting relations between our results and Shannon's theory on discrete noiseless channels (DNC)s. The DNCs can be thought as the "asynchronous" versions of the our units.

REFERENCES

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