Maximum Entropy Principle for Physical Systems

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In thermodynamic equilibrium, the probability distribution will be the solution to the optimization problem:

Maximize
$$S = -k_B \sum_{k=1}^{n} p_k \ln p_k$$
 (1)

subject to the constraints

$$\sum_{i=1}^{n} p_{i} E_{i} = E$$

$$\sum_{i=1}^{n} p_{i} = 1$$
(2)

$$\sum_{i=1}^{n} p_i = 1 \tag{3}$$

$$p_i \ge 0, \quad 1 \le i \le n \tag{4}$$

Lagrange Multipliers for Physical Systems

We ignore the constraint $p_i \ge 0$ and will find that it automatically is satisfied for this problem.

In order to make the Lagrange multipliers agree with those in the lecture notes, we maximize instead

$$\phi(\mathbf{p}) = -\sum_{k=1}^{n} p_k \ln p_k \tag{5}$$

Lagrange multipliers tell us the maximum will be found at the point (or, in general, among the several points) where

$$\nabla \phi(\mathbf{p}) = \alpha' \nabla \left(\sum_{i=1}^{n} p_i \right) + \beta \nabla \left(\sum_{i=1}^{n} p_i E_i \right), \tag{6}$$

i.e.,

$$\frac{\partial \phi}{\partial p_{j}} = \alpha' \frac{\partial}{\partial p_{j}} \left(\sum_{i=1}^{n} p_{i} \right) + \beta \frac{\partial}{\partial p_{j}} \left(\sum_{i=1}^{n} p_{i} E_{i} \right). \tag{7}$$

Evaluating the derivatives, for each value of j,

$$\frac{\partial \phi}{\partial p_{j}} = \frac{\partial}{\partial p_{j}} \left(-\sum_{k=1}^{n} p_{k} \ln p_{k} \right) = -\left(\ln p_{j} + 1 \right)$$
(8)

$$\frac{\partial}{\partial p_j} \sum_{i=1}^n p_i = 1 \tag{9}$$

$$\frac{\partial}{\partial p_j} \sum_{i=1}^n p_i E_i = E_j \tag{10}$$

Substituting (8), (9) and (10) into (7) gives, for each j,

$$-(\ln p_i + 1) = \alpha' + \beta E_i \tag{11}$$

$$\ln p_j = -(\alpha' + 1) - \beta e_j = -\alpha - \beta E_j \tag{12}$$

$$p_j = e^{-\alpha} e^{-\beta E_j} \tag{13}$$

This gives the general form of the maximum entropy solution. The remaining goal is to choose α and β so that both constraints (2) and (3) are satisfied.

Satisfying constraint (3) that the probabilities sum to 1 lets us eliminate α :

$$\sum_{j=1}^{n} p_{j} = \sum_{j=1}^{n} e^{-\alpha} e^{-\beta E_{j}} = e^{-\alpha} \sum_{j=1}^{n} e^{-\beta E_{j}} = 1,$$
 (14)

SO

$$e^{-\alpha} = \frac{1}{\sum_{j=1}^{n} e^{-\beta E_j}},$$
(15)

i.e., the general solution has the form

$$p_{j}^{*} = \frac{e^{-\beta E_{j}}}{\sum_{j=1}^{n} e^{-\beta E_{j}}}, \quad 1 \le j \le n,$$
(16)

where p_j^* indicates the value of p_j that maximizes the entropy. The Lagrange multiplier method works and the form of the solution is still valid if there are infinitely many energy states, $n \to \infty$. Since the energies are all positive, we see that with infinitely many energies we must have

 $\beta > 0$ so the probabilities can be normalized. In that case the probability a given state is occupied shrinks exponentially with its energy. But with a finite number of energies it is also possible to have $\beta < 0$ and for the probability a state is occupied to *grow* exponentially with its energy. The phenomenon, called *population inversion*, underlies the operation of all lasers.

A General Feature of Lagrange Multipliers

A general geometric feature of the solution to Lagrange multiplier problems will help us interpret β . Lets begin with a simple example:

Maximize
$$\phi(x, y)$$
 (17)

subject to

$$g(x,y) = ax + by = G ag{18}$$

Lagrange multipliers tells us that the optimal solution will be found at a point where, for some λ ,

$$\nabla \phi(x, y) = \lambda \nabla g(x, y), \tag{19}$$

i.e.,

$$\frac{\partial \phi}{\partial x}(x,y) = \lambda \frac{\partial g}{\partial x}(x,y) = \lambda a \tag{20}$$

$$\frac{\partial \phi}{\partial y}(x,y) = \lambda \frac{\partial g}{\partial y}(x,y) = \lambda b, \tag{21}$$

i.e.,

$$\nabla \phi(x, y) = \lambda \binom{a}{b} \tag{22}$$

Example

Maximize
$$\phi(x,y) = x^2 + y^2$$
 (23)

subject to
$$g(x,y) = x + 2y = 5$$
 (24)

$$\nabla \phi = \begin{pmatrix} 2x \\ 2y \end{pmatrix} = \lambda \nabla g = \lambda \begin{pmatrix} 1 \\ 2 \end{pmatrix} \tag{25}$$

$$2x = \lambda$$
$$2y = 2\lambda,$$

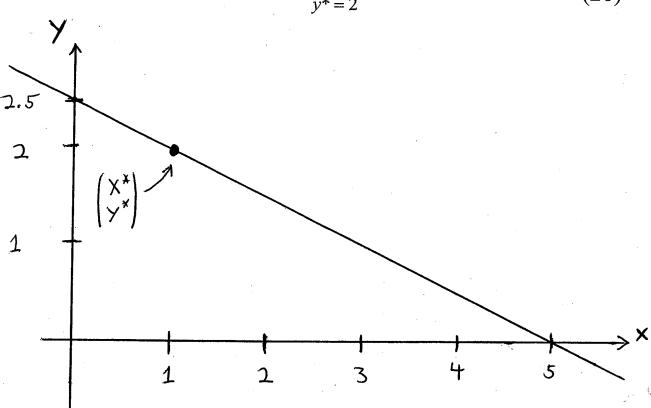
i.e.,

$$y = 2x$$

$$5 = x + 2y = x + 4x = 5x$$

$$x^* = 1$$

$$y^* = 2$$
(26)



Sensitivity to Constraints

Suppose we alter the optimum solution

$$\begin{pmatrix} x^* \\ y^* \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$
 (27)

to some nearby point

$$\begin{pmatrix} x^* + \delta x \\ y^* + \delta y \end{pmatrix}, \tag{28}$$

The nearby point might be a nonoptimal value, or it might be the optimal solution subject to the altered value of the constraint

$$g(x,y) = G + \delta G \tag{29}$$

How do ϕ and g change as we move to the nearby point? By the chain rule for calculus

$$\delta\phi = \frac{\partial\phi}{\partial x}(x^*, y^*)\delta x + \frac{\delta\phi}{\partial y}(x^*, y^*)\delta y \tag{30}$$

$$= (\nabla \phi)_{(x^*, y^*)} \bullet \begin{pmatrix} \delta x \\ \delta y \end{pmatrix} \tag{31}$$

and

$$\delta g = \frac{\delta g}{\partial x} (x^*, y^*) \delta x + \frac{\partial g}{\partial y} (x^*, y^*) \delta y =$$

$$(\nabla g)_{(x^*, y^*)} \cdot \begin{pmatrix} \delta x \\ \delta y \end{pmatrix}.$$
(32)

But by the principle of Lagrange multipliers,

$$\nabla \phi(x^*, y^*) = \lambda \nabla g(x^*, y^*), \tag{33}$$

and therefore

$$\delta\phi = (\nabla\phi) \cdot \begin{pmatrix} \delta x \\ \delta y \end{pmatrix} = \lambda (\nabla g) \cdot \begin{pmatrix} \delta x \\ \delta y \end{pmatrix} = \lambda \delta g, \tag{34}$$

Lagrange Multiplier Sensitivity Principle

For *any* small perturbation about the optimal solution to a Lagrange multiplier problem with a single constraint

$$\frac{\delta\phi}{\delta g} = \lambda \tag{35}$$

Interpretation of β

Returning to our original problem

maximize
$$\phi(\mathbf{p}) = -\sum_{k=1}^{n} p_k \ln p_k$$
 (36)

subject to

$$g_1(\mathbf{p}) = \sum_{i=1}^n p_i = 1 \tag{37}$$

$$g_2(\mathbf{p}) = \sum_{i=1}^n p_i E_i = E \tag{38}$$

at the optimum solution p^* we have

$$\nabla \phi(\mathbf{p}^*) = \alpha \nabla g_1(\mathbf{p}^*) + \beta \nabla g_2(\mathbf{p}^*)$$
(39)

and therefore for *any* small perturbation to $(p^*+\delta p)$ we have

$$\delta\phi = (\nabla\phi) \cdot (\delta \mathbf{p}) = \alpha (\nabla g_1) \cdot (\delta \mathbf{p}) + \beta (\nabla g_2) \cdot (\delta \mathbf{p}) = \alpha \delta g_1 + \beta \delta g_2$$

$$\delta\phi = \alpha \delta g_1 + \beta \delta g_2$$

$$(41)$$

In particular, for any perturbation δp such that $p^* + \delta p$ is a valid probability distribution, i.e.,

$$\sum_{i=1}^{n} (p_i * + \delta p_i) = 1$$
 (42)

$$\delta g_1 = \sum_{i=1}^n \delta p_i = 0, \tag{43}$$

we have

$$\delta \phi = \beta \delta g_2 = \beta \delta \left(\sum_{i=1}^n p_i E_i \right) = \beta \delta E. \tag{44}$$

$$\beta \sum_{i=1}^{n} E_{i} \delta p_{i} = \beta \delta E$$

Recalling that our original goal was to maximize

$$S = k_B \phi = -k_B \sum_{k=1}^{n} p_k \ln(p_k),$$
 (45)

for any such perturbation about p^* ,

$$\delta S = k_B \beta \delta E \tag{46}$$

$$\left| \frac{\delta S}{\delta E} = k_B \beta \right|$$
(47)

Looking ahead to a comparison with classical thermodynamics, where temperature plays the role

$$\frac{\partial E}{\partial S} = T, \text{ in degrees Kelvin,} \tag{48}$$

we anticipate that

$$k_{\rm B}\beta = \frac{1}{T} \tag{49}$$

$$\beta = \frac{1}{k_B T} \tag{50}$$

and therefore

$$p_{k}^{*} = \frac{e^{-E_{k}/k_{B}T}}{\sum_{k=1}^{n} e^{-E_{k}/k_{B}T}}.$$
(51)